

# Math 132: Differential Topology

## § Lefschetz fixed point theorem

Let  $M$  be a compact, oriented manifold, and  $f: M \rightarrow M$  a smooth map.

The global Lefschetz number of  $f$ , denoted  $L(f)$ , is

$$\underline{L(f) = I(\Delta, \text{graph}(f))}.$$

The followings are immediate consequences of the intersection theory:

Prop  $L(f)$  is a homotopy invariant.

Thm (smooth Lefschetz fixed point theorem)

If  $L(f) \neq 0$ , then  $f$  has a fixed point.

fixed points of  $f$

$\Downarrow$   
intersection points  $\Delta \cap \text{graph}(f)$

Prop If  $f$  is homotopic to the identity, then  $L(f) = \chi(M)$ .

In particular, if  $M$  admits a smooth map  $f: M \rightarrow M$  homotopic to the identity that has no fixed points, then  $\chi(M) = 0$ .

Ex Rotation of  $S^1$  by an angle  $\theta \neq 0 \pmod{2\pi}$  has no fixed points, so  $\chi(S^1) = 0$ .

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We say a map  $f: M \rightarrow M$  is Lefschetz if  $\Delta \pitchfork \text{graph}(f)$ .

Clearly,

Prop Every map  $f: M \rightarrow M$  is homotopic to a Lefschetz map.

Note,  $\Delta \pitchfork \text{graph}(f)$  at  $(x, x) \Leftrightarrow \Delta_x + \text{graph}(df_x) = T_x M \times T_x M$

$$\Leftrightarrow \Delta_x \cap \text{graph}(df_x) = 0$$

$$\Leftrightarrow df_x \text{ has no eigenvector of eigenvalue } 1$$

(i.e.  $\det(df_x - I) \neq 0$ )

We say a fixed point  $x$  of  $f$  is a Lefschetz fixed point if  $\nearrow$  holds.

For a Lefschetz fixed point  $x$  of  $f$ , the local Lefschetz number of  $f$  at  $x$ ,

$L_x(f)$ , is the orientation number  $\in \{\pm 1\}$  of  $(x, x) \in \Delta \cap \text{graph}(f)$ .

Clearly, for Lefschetz maps,

$$L(f) = \sum_{f(x)=x} L_x(f).$$

$\longleftarrow$  sum over fixed points.

Prop  $L_x(f) = \text{sign}(\det(df_x - I))$ .

proof) The proof is a simple linear algebra: if  $\{v_1, \dots, v_m\}$  is a positively oriented ordered basis for  $T_x M$ , then

$$\begin{aligned} L_x(f) &= \text{sign} \left\{ \underbrace{(v_1, v_1), \dots, (v_m, v_m)}_{\text{positive for } T_{(x,x)} \Delta}, \underbrace{(v_1, df_x(v_1)), \dots, (v_m, df_x(v_m))}_{\text{positive for } T_{(x,x)} \text{graph}(f)} \right\} \\ &= \text{sign} \left\{ (v_1, v_1), \dots, (v_m, v_m), (0, (df_x - I)v_1), \dots, (0, (df_x - I)v_m) \right\} \\ &= \text{sign} \left\{ (v_1, 0), \dots, (v_m, 0), (0, (df_x - I)v_1), \dots, (0, (df_x - I)v_m) \right\} \\ &= \text{sign}(\det(df_x - I)). \quad \blacksquare \end{aligned}$$

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Ex (local pictures in 2d)

Assume that  $df_x = \begin{pmatrix} \alpha_1 & 0 \\ 0 & \alpha_2 \end{pmatrix}$  with  $\alpha_1, \alpha_2 > 0$ .

Case 1: If either  $\alpha_1, \alpha_2 > 1$  or  $\alpha_1, \alpha_2 < 1$ , then  $L_x(f) = +1$ .

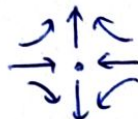


source



sink

Case 2: If  $\alpha_1 < 1 < \alpha_2$ , then  $L_x(f) = -1$



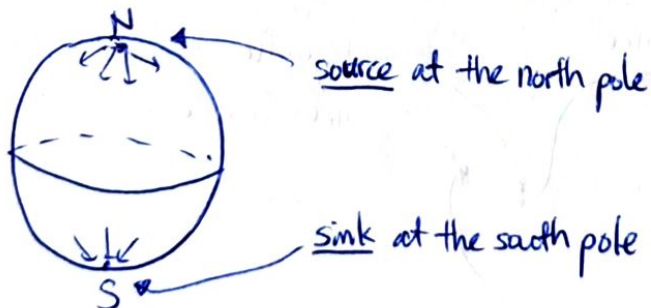
saddle

Ex (Euler characteristic from local Lefschetz numbers)

Consider the map  $f: S^2 \rightarrow S^2$  given by a "downward flow"

$$f_t(x) = \pi \left( x + (0, 0, -\frac{t}{2}) \right), \quad 0 < t < 2,$$

where  $\pi: \mathbb{R}^3 \setminus \{0\} \rightarrow S^2$  is the projection.



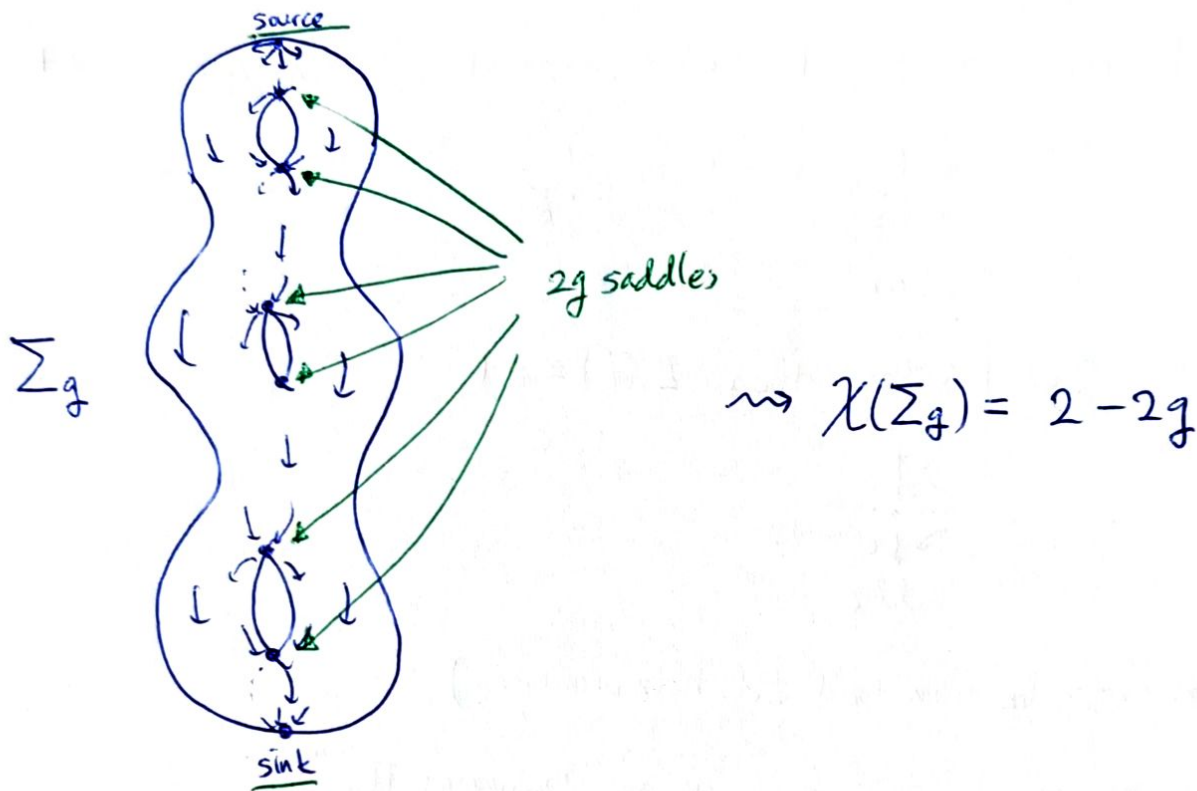
$$\rightsquigarrow \chi(S^2) = L(f, \cdot) = 1 + 1 = 2.$$

Cor Every map  $f: S^2 \rightarrow S^2$  homotopic to the identity must have a fixed point.

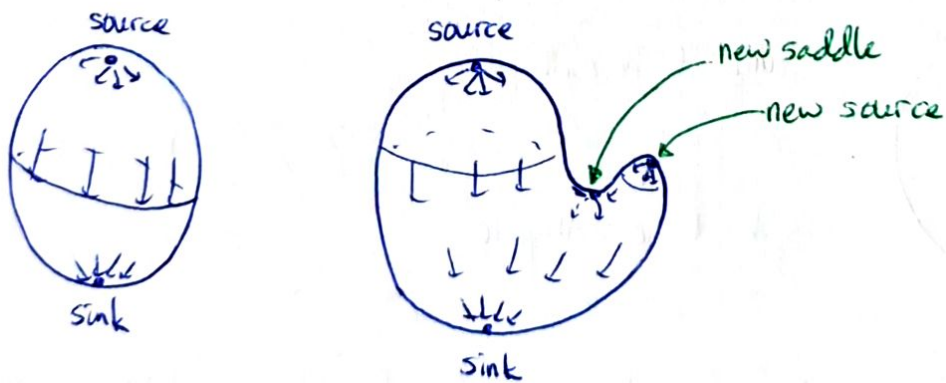
In particular, the antipodal map  $x \mapsto -x$  is not homotopic to the identity.

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More generally, a genus  $g$  surface admits a Lefschetz map homotopic to the identity that has 1 source, 1 sink, and  $2g$  saddles:



It is also instructive to see how the fixed points get created and annihilated in pairs when we deform the "height function":



$$\chi(S^2) = 1 + 1 = 1 + 1 + (1 - 1)$$